

Differential Equations

9/14/2020

HW 4 due Friday 9/18 @ midnight EST

Office Hours tomorrow (Tues) 1:30-2:30pm EST

- Reminder Midterm #1 Tues 9/29 - Thur 10/1
48 hr. noon EST - noon EST

Practice Midterms on Canvas → File →
"Practice Exams"

Please do Poll

$$\int u dv = uv - \int v du$$

$$\int t \cos t dt$$

$$\begin{array}{l} u = t \quad v = \sin t \\ du = dt \quad dv = \cos t dt \end{array}$$

Second Order Differential Equations

$y'' = f(t, y, y')$ normal form

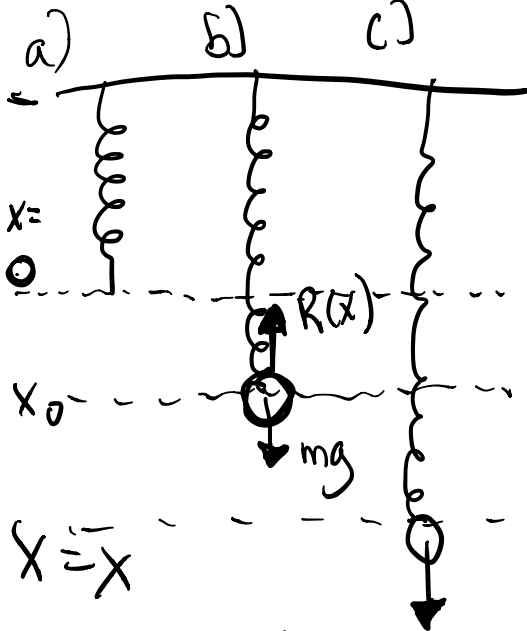
$y' = f(t, y)$ recall

generally:

$y'' + p(t)y' + q(t)y = g(t)$

linear, inhomogeneous ↑ forcing term
 can't separation of variables

if $g(t) = 0$ homogeneous



a) Spring w/ no mass
spring-equilibrium → no motion, $x=0, x'=0$
 below x positive

b) attached a weight
 stretches spring,
 new equilibrium at
 $x = x_0, x' = 0$

c) Spring is stretched
 weight is not
 in equilibrium
 $v = x'$

Spring-mass equilibrium
 gravity down, "restorative force/spring force up"

$\Sigma F = 0 = R(x_0) + mg = 0$

also damping D (resistance to motion of mass through air/medium)
 $D(v)$, if not moving $D=0$

there can also be an external force $F(t)$

$$ma = \text{total force acting on weight}$$
$$ma = \underbrace{R(x)}_{\text{spring}} + mg + \underbrace{D(v)}_{\text{damping}} + F(t)$$

$$a = \ddot{x} \quad v = \dot{x}$$

$$\rightarrow m \ddot{x} = \underline{R(x)} + mg + D(\dot{x}) + F(t)$$

Hooke's Law:

$$R(x) = -Kx \quad K > 0$$

acts to decrease displacement of the mass (only valid for small displacements)
constant \rightarrow

$$m \ddot{x} = -Kx + mg + D(\dot{x}) + F(t)$$

case w/no external force ($F(t)=0$)
and in spring-mass equilibrium

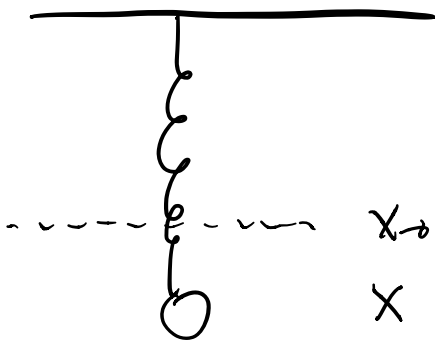
$$x = x_0, \quad \dot{x} = \ddot{x} = 0$$

$$0 = -kx_0 + mg$$

$$kx_0 = mg$$

$$K = \frac{mg}{x_0}$$

$$m\ddot{x} = -K(x - x_0) + D(\dot{x}) + F(t)$$



redefine:

$$y = x - x_0$$

$$\dot{y} = \dot{x}$$

$$\ddot{y} = \ddot{x}$$

$$m\ddot{y} = -ky + D(\dot{y}) + F(t)$$

$$D(\dot{y}) = -\mu v = -\mu \dot{y}$$

goes against velocity

μ is non negative

= often a constant

$$m\ddot{y} + ky + \mu\dot{y} = F(t)$$

$$m\ddot{y} + ky = 0$$



$$\ddot{y} = -\left(\frac{k}{m}\right)y$$

$$\begin{array}{l}
 \sin(At) \xrightarrow{\frac{d}{dt}} A \cos(At) \xrightarrow{\frac{d}{dt}} -A^2 \sin(At) \\
 \cos(At) \xrightarrow{\frac{d}{dt}} -A \sin(At) \xrightarrow{\frac{d}{dt}} -A^2 \cos(At)
 \end{array}$$

general solution

$$y(t) = a \cos(\sqrt{\frac{K}{m}} t) + b \sin(\sqrt{\frac{K}{m}} t)$$

$$\ddot{y} = -\frac{K}{m} y$$

$$\sqrt{\frac{K}{m}} = \omega_0 \quad \text{natural frequency}$$

$$\text{period} \rightarrow \boxed{T = \frac{2\pi}{\omega_0}}$$

$$v = f = \text{numerical frequency} = \frac{\text{cycles}}{\text{second}} = \frac{1}{T} = \frac{\omega_0}{2\pi}$$

General Solution to 2nd Order Diff Eq

$$y'' + p(t)y' + q(t)y = 0$$

→ y_1, y_2 are both solutions to homogeneous equation

also a solution → $y = C_1 y_1 + C_2 y_2$

a linear combination of two solutions with C_1, C_2 constants

* Any linear combination of two solutions is also a solution

Ex $y'' - y' - 2y = 0$

if $y_1(t) = e^{-t}$ $y_2(t) = e^{2t}$ are solutions

then $y(t) = C_1 e^{-t} + C_2 e^{2t}$ is also a solution

$$\frac{d^2}{dt^2} [C_1 e^{-t} + C_2 e^{2t}] - \frac{d}{dt} [C_1 e^{-t} + C_2 e^{2t}] - 2[C_1 e^{-t} + C_2 e^{2t}] = 0$$

$$+C_1 e^{-t} + 4C_2 e^{2t} = (-C_1 e^{-t} + 2C_2 e^{2t}) - 2[C_1 e^{-t} + C_2 e^{2t}] = 0$$

$$\cancel{C_1 e^{-t}} + 4C_2 e^{2t} + \cancel{C_1 e^{-t}} - 2C_2 e^{2t} - 2\cancel{C_1 e^{-t}} - 2\cancel{C_2 e^{2t}} = 0$$

$$0 = 0 \checkmark$$

linearly independent

u, v are said to be linearly independent if neither is a constant multiple of the other on some interval (α, β)

ex $u(t) = t$ and $v(t) = t^2$

$$\frac{u}{v} = \frac{t}{t^2} = \frac{1}{t} \quad \text{not a constant}$$

are linearly independent

$$U(t) = \underline{\sin(t)} \quad V(t) = \underline{\underline{-4\sin(t)}}$$

$$\frac{U}{V} = \frac{\sin(t)}{-4\sin(t)} = -\frac{1}{4}$$

linearly dependent \times

two linearly independent solutions
form a fundamental set of solutions

$$y = C_1 y_1 + C_2 y_2$$

Wronskian of two functions
 $u, v,$

$$W(t) = \det \begin{pmatrix} u(t) & v(t) \\ u'(t) & v'(t) \end{pmatrix} = \underline{u \cdot v' - u'v}$$

$$\det \begin{vmatrix} a & b \\ c & d \end{vmatrix} = ad - bc$$

$W(t) = 0$ u, v linearly dependent

$W(t) \neq 0$ u, v linearly independent

linear homogeneous Equations with
constant coefficients

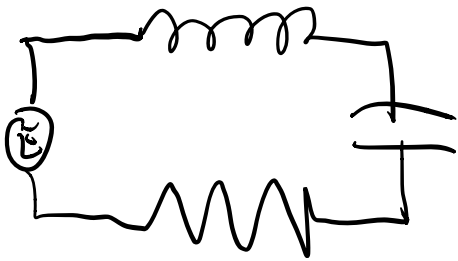
$$y'' + p(t)y' + q(t)y = 0$$

$$y'' + p y' + q y = 0$$

$p \geq 0$ constants
 $q > 0$

$$I'' + \frac{R}{L} I' + \frac{1}{LC} I = 0$$

RLC equation



$$y'' + \mu y' + \frac{k}{m} y = 0$$

unforced
vibrating
spring